

On Mean Values and Geometrical Probabilities in E_n .

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Introduction. In this report V.3, pp.35–43, we treated the subject in the Euclidean three-space E_3 [5].* The aim of the present paper is to generalize my previous result [5] in an Euclidean n -space E_n . For the purpose, we shall first define the uniform-figure-systems in E_n in the same manner as before, and discuss the subject under classified cases.

§ 1. Definition

1.1. Covering of Euclidean Space E_n .

Let σ_0 be a closed hypersurface in the Euclidean n -space E_n . Let us define a discontinuous rigid motion T_1 which operates upon σ_0 and satisfies with the following condition (a). Let us begin with marking σ_0 at its initial position in E_n . If we operate T_1 upon σ_0 , σ_0 will move to the next position. Again, let us mark σ_0 at such a position.

Let us set the following condition (a), that is ; (a) *The two adjacent surfaces have a part of them in common but neither of them has any inner point of the domain enclosed by the other surface in common.* Let us operate T_1 and T_1^{-1} upon σ_0 in the same direction**) i_1 -times in all, then we obtain a tubiform surface σ_1 which is joined by i_1 -pieces of σ_0 piece by piece. Subsequently, let us define another rigid motion T_2 which operates upon σ_1 in a direction which is independent of that of T_1 and satisfies with the condition (a). Again, operating T_2 and T_2^{-1} upon σ_1 i_2 -times in all, we obtain a leaf-like hypersurface which is composed of i_2 -pieces of σ_1 piece by piece. Let us denote this leaf-like hypersurface by σ_2 .

In such a manner, let us suppose that the construction, by means of which a series $\{\sigma_k\}$ of hypersurfaces and a series $\{T_k\}$ of discontinuous rigid motions of which T_k operates upon σ_{k-1} i_k -times in common with T_k^{-1} and satisfies the condition (a), are defined, in succession, $k=1,2,\dots,n$, and a closed hypersurface σ_n is obtained at last. Then σ_n will be composed of $i_1 i_2 \dots i_n$ -pieces of surfaces congruent to σ_0 , or in other words, the whole domain which is enclosed by σ_n is divided into $i_1 i_2 \dots i_n$ -pieces each of which is congruent to the domain enclosed by σ_0 without overlapping or without

*) Number in brackets refer to the bibliography at the end of the paper.

**) It can be proved that any given rigid motion in E_n is the resultant of a uniquely defined rotation and a uniquely defined translation along the axis of the rotation.

leaving gaps. After this construction, if we increase i_1, i_2, \dots, i_{n-1} and i_n to infinity simultaneously, the whole space E_n is covered by ∞^n -pieces of domains, each being congruent to the domain enclosed by σ_0 , without overlapping or without leaving gaps. Now let us call such a construction "a covering of E_n by σ_0 ", the domain ϑ enclosed by σ_0 , "a fundamental cell" in the covering and each domain which is arranged by the covering, "a unit cell" in the covering.

1.2. Uniform Figure Systems

Connecting with the above covering of E_n by σ_0 , let us define the uniform arrangements of figures. For the purpose, let us prepare the following figure-set:

- (k) A set $\mathfrak{E}^k = \{f_j^k\}$ of k -dimensional manifolds $f_j^k (j = 1, 2, \dots, p), p < \infty$ and the sum*) of k -dimensional measure of $f_j^k (j = 1, 2, \dots, p)$ is finite.

Explaining in detail, the meaning of the above definition is as follows. For $k=0$, f_j^0 reduces a point and the sum of zero-dimensional measure of f_j^0 's is equal to the number of these points, namely p . For $k=1$, f_j^1 reduces a curve and the one-dimensional measure of f_j^1 is equal to its curve length, and so forth. Now, if we cover E_n by a fundamental cell σ_0 attached with a set \mathfrak{E}^k of k -dimensional manifolds, every unit cell will be allotted with a figure set \mathfrak{E}^k .

At this time, let us select the figure set \mathfrak{E}^k in the covering of E_n by σ_0 with \mathfrak{E}^k , (β) every figure set at all unit cells may not intersect with any set at another cells. Now, in such a covering of E_n by σ_0 attached with a figure set \mathfrak{E}^k , let us call an original set \mathfrak{E}^k of k -dimensional manifolds, by the name of "the fundamental figure" and every one allotted to each unit cell, "the unit figure." In consequence, we shall obtain such a uniform arrangement of the unit figure allotted to each unit cell in whole space E_n .

In the end, let us cross out all the covering hypersurfaces, then we obtain a uniform arrangement of a unique figure set \mathfrak{E}^k in E_n . Let us classify such a uniform arrangement of σ_k in E_n corresponding to the kind of the fundamental figure (k) by calling "uniform- k -dimensional manifold-system in E_n ". Hence,

- (0) a uniform-point-system,
- (1) a uniform-curve-system,
- (2) a uniform-surface-system,
-
- (k) a uniform- \mathfrak{E}^k -system
-
- (n-1) a uniform-hypersurface-system.

§ 2. Uniform-Point-System in E_n

2.1 Set of points of a finite number. Let \mathfrak{E}^0 be a set $\{P_j\}$ of points $P_i (i=1, 2, \dots, \rho)$ which are fixed in E_n and \mathfrak{R} a closed hypersurface whose n -dimensional enclosed volume

*) We shall speak it by calling k -dimensional measure of in the following.

is V and which moves in E_n .

Then, using the kinematic density, by W. Blaschke [1]

$$\dot{\mathfrak{R}} = \prod_{i=1}^n \dot{s}_i \prod_{j=1}^{n-1} \dot{\omega}_j, \quad (1)$$

we can obtain the following formula, which represents the total measure of positions of moving \mathfrak{R} by which a fixed point P is contained, that is,

$$\int_{p \in \mathfrak{R}} \dot{\mathfrak{R}} = \Omega_n \cdot V, \quad (2)$$

where

$$\Omega_n = \omega_1 \omega_2 \dots \omega_{n-1} = \frac{2^{n-1} \pi^{\frac{1}{4}(n+2)(n-1)}}{\Gamma(\frac{n}{2}) \Gamma(\frac{n-1}{2}) \dots \Gamma(\frac{2}{2})}, \quad \omega_i = \frac{2\pi^{\frac{i+1}{2}}}{\Gamma(\frac{i+1}{2})} \quad (3)$$

Then the total measure of the positions of \mathfrak{R} which contains some points of \mathfrak{S} is given by the formula

$$\int_{\mathfrak{S} \cap \mathfrak{R} \neq \emptyset} m \dot{\mathfrak{R}} = \rho \Omega_n V, \quad (4)$$

where m represents the number of the points of \mathfrak{S} contained in \mathfrak{R} at a position and the integration is extended all over the intersection points of \mathfrak{S} and \mathfrak{R} .

2.2 Uniform-point-system and moving surface.

(1). Let us take a uniform-point-system in E_n which is defined by the fundamental cell attached with ρ -points and move a closed hypersurface \mathfrak{R} whose n -dimensional volume is V .

Let us estimate the mean value of the number of points belonging to the system which are contained by \mathfrak{R} at a position.

Let us proceed our treatment comparing with my previous paper [5] in E_3 .

(2) In the same manner with that in the case of E_3 , let us begin with the definition of the domain \mathfrak{U} which consists of $\mu_1 \mu_2 \dots \mu_n$ -pieces of unit-cell. Here μ_i -pieces are lying along the direction corresponding to T_i . Then, we obtain a point-set $\mathfrak{P}_{\mathfrak{U}}$ belonging to the system which is contained in the domain \mathfrak{U} and consists of $\rho \prod_{i=1}^n \mu_i$ points.

Hereupon, defining two domains $\overline{\mathfrak{U}}$ and $\overline{\overline{\mathfrak{U}}}$ after the analogy to the case E_3 , we can obtain the superset $\mathfrak{P}_{\mathfrak{U}}$ and the subset $\mathfrak{P}_{\overline{\mathfrak{U}} - \overline{\overline{\mathfrak{U}}}}$ to the set $\mathfrak{P}_{\mathfrak{U}}$. Here, $\mathfrak{P}_{\mathfrak{U}}$ consists of

$\rho \prod_{i=1}^n (\mu_i + 2\nu_i)$ -points of the system and $\mathfrak{P}_{\overline{\mathfrak{U}} - \overline{\overline{\mathfrak{U}}}}$, $\rho \left\{ \prod_{i=1}^n (\mu_i + 2\nu_i) - \prod_{i=1}^n (\mu_i - 2\nu_i) \right\}$ -points of the system.

(3) Under these preparations, let us estimate the mean value of the number of points of the uniform-point-system which are contained by a moving closed hypersurface \mathfrak{R} . First, applying (4) for the point-set $\mathfrak{P}_{\mathfrak{U}}$, we obtain

$$\int_{\mathfrak{P}_{\mathfrak{U}} \cap \mathfrak{R} \neq \emptyset} m \dot{\mathfrak{R}} = \rho \Omega_n V \prod_{i=1}^n (\mu_i + 2\nu_i) \quad (5)$$

where ρ denotes the number of points of the system in a unit cell ϑ , V the enclosed volume by \mathfrak{R} and Ω_n is given by (3).

If we divide the integral at the left side of (5) into two parts $I_{P \in \mathfrak{U}}$ and $I_{P \in \overline{\mathfrak{U}} - \overline{\overline{\mathfrak{U}}}}$: $I_{P \in \mathfrak{U}}$ is

such a total measure of the position of \mathfrak{R} as the origin P attached to \mathfrak{R} is contained in \mathfrak{U} and $I_{P \in \alpha}$ is the rest of the integral. Then, we can rewrite (5), as follows,

$$I_{P \in \alpha} + I_{P \notin \alpha} = \rho \Omega_n V \prod_{i=1}^n (\mu_i + 2\nu_i). \quad (6)$$

In the same way as before, if we represent by $\int_{P \in \vartheta} m \dot{\mathfrak{R}}$ the total measure of positions of \mathfrak{R} so that P attached to \mathfrak{R} may be contained in a unit cell ϑ and \mathfrak{R} may contain $m (\geq 1)$ -points of the system, we can express $I_{P \in \alpha}$, as follows,

$$I_{P \in \alpha} = \prod_{i=1}^n \mu_i \int_{P \in \vartheta} m \dot{\mathfrak{R}} \quad (7)$$

On the same account as before, we can put

$$I_{P \notin \alpha} \leq \rho \Omega_n V \left\{ \prod_{i=1}^n (\mu_i + 2\nu_i) - \prod_{i=1}^n (\mu_i - 2\nu_i) \right\},$$

and therefore

$$\lim_{\mu_i \rightarrow \infty} \frac{I_{P \notin \alpha}}{\prod_{i=1}^n \mu_i} = 0 \quad (8)$$

Now, if we divide the both members of (6) by $\prod_{i=1}^n \mu_i$ and take account of (7) and (8), we obtain the following equation as the limit equation as $\mu_i \rightarrow \infty$ ($i=1, 2, \dots, n$)

$$\int_{P \in \vartheta} m \dot{\mathfrak{R}} = \rho \Omega_n V. \quad (9)$$

On the other hand, the total measure of \mathfrak{R} at such positions P attached to \mathfrak{R} is contained in a unit cell ϑ is given as follows,

$$\int_{P \in \vartheta} \dot{\mathfrak{R}} = \Omega_n C^* \quad (10)$$

where C denotes the volume of a unit cell ϑ .

Hence, dividing (9) by (10), we obtain the following theorem.

THEOREM 1. *When a closed hypersurface \mathfrak{R} of the n -dimensional volume V moves in E_n where a uniform-point-system is defined, the mean value \bar{m} of the number of points of the system contained in \mathfrak{R} , is given by*

$$\bar{m} = \rho \frac{V}{C}, \quad (11)$$

where ρ denotes the number of points belonging to a unit cell and the volume of a unit cell.

It is a matter of course that the above theorem comprises the corresponding cases of $n=2$ [3], or 3 [5] as its special case, and \bar{m} is given by the same expression independently of the dimension of the space.

Consequently, in the special case in which the number of points contained by \mathfrak{R} under these configuration, is exclusively limited to m_1 or m_2 ($m_1 > m_2 \geq 0$), the probability P_1 for the case that the number in question is m_1 is given $P_1 = \frac{\rho V - C m_2}{C(m_1 - m_2)}$ in every

*) In order to save trouble of reexplanation of the same procedure, we shall speak of the equation (10) as „a limit equation by covering procedure of the whole space E_n with the equation (4)“.

number of dimension.

§ 3. Uniform- \mathcal{E}^k -System and Moving Manifold \mathbb{R}^r .

3.1. Mean value of the measure $S_{k+r-n}(\mathcal{E}^k \cap \mathbb{R}^r)$.

(1) In E_n Let us define a uniform- \mathcal{E}^k -system which is constructed by the fundamental figure-set \mathcal{E}^k of k -dimensional manifolds f_j^k ($j=1,2,\dots, p$), and move a r -dimensional manifold \mathbb{R}^r whose r -dimensional volume is finite. Now, we assume that $r+k-n \geq 0$ and let $\mathcal{E}^k \cap \mathbb{R}^r$ be the $(r+k-n)$ -dimensional manifolds of the intersection of some of \mathcal{E}^k 's with \mathbb{R}^r and $S_{k+r-n}(\mathcal{E}^k \cap \mathbb{R}^r)$ $(k+r-n)$ -dimensional volume of the intersection $\mathcal{E}^k \cap \mathbb{R}^r$. Here, when $r+k-n=0$, $S_0(\mathcal{E}^k \cap \mathbb{R}^r)$ denotes the number of intersection points of $\mathcal{E}^k \cap \mathbb{R}^r$. Then let us estimate the mean value $S_{k+r-n}(\mathcal{E}^k \cap \mathbb{R}^r)$ of $S_{k+r-n}(\mathcal{E}^k \cap \mathbb{R}^r)$.

(2) At this time, we have a satisfactory formula [4] by L. A. Santaló. Adjusting it to the present case, we can express it as follows. Let C^k be a fixed k -dimensional manifold and \mathbb{R}^r a moving r -dimensional manifold in E_n . If $r+k-n \geq 0$, we have

$$\int_{C^k \cap \mathbb{R}^r \neq \emptyset} S_{k+r-n}(C^k \cap \mathbb{R}^r) \dot{\mathbb{R}} = \frac{\Omega_{n+1} \omega_{r+k-n}}{\omega_k \omega_r} S_k(C^k) S_r(\mathbb{R}^r), \quad (12)$$

where

$$\Omega_{n+1} = \omega_1 \omega_2 \cdots \omega_{n-1} \omega_n, \quad \omega_i = \frac{2\pi^{\frac{i+1}{2}}}{\Gamma(\frac{i+1}{2})}.$$

Further, let us use the following formula by L. A. Santaló [4] which gives expression to the total measure of positions of \mathbb{R}^r which leave a point of \mathbb{R}^r invariant. That is,

$$\int_{Total} d\mathbb{R}^{r(P)} = \Omega_n. \quad (13)$$

(3) Let us find the mean value of $S_{k+r-n}(\mathcal{E}^k \cap \mathbb{R}^r)$. In the covered space E_n , let us take a domain \mathfrak{A} which contains $\prod_{i=1}^n \mu_i$ -pieces of unit cell \mathcal{V} and a figure-set $\mathcal{E}_{\mathfrak{A}}^k$ which is consisted of $\prod_{i=1}^n \mu_i$ -pieces of unit figure \mathcal{E}^k . And then two domains $\overline{\mathfrak{A}}$ and $\overline{\overline{\mathfrak{A}}}$, or a figuresuperset $\mathcal{E}_{\overline{\mathfrak{A}}}^k$ and a subset $\mathcal{E}_{\overline{\overline{\mathfrak{A}}}}^k$ are determined with reference to \mathbb{R}^r . Then, using (12), we have

$$\int_{\mathcal{E}_{\overline{\mathfrak{A}}}^k \cap \mathbb{R}^r \neq \emptyset} S_{k+r-n}(\mathcal{E}_{\overline{\mathfrak{A}}}^k \cap \mathbb{R}^r) \dot{\mathbb{R}} = \frac{\Omega_{n+1} \omega_{k+r-n}}{\omega_k \omega_r} S_k(\mathcal{E}^k) S_r(\mathbb{R}^r) \prod_{i=1}^n (\mu_i + 2\nu_i). \quad (14)$$

Now, in the same maner as in § 2.2, (2), let us denote by $\int_{P \in \mathcal{P}} S_{k+r-n}(\mathcal{E}_{\mathfrak{A}}^k \cap \mathbb{R}^r) \dot{\mathbb{R}}$ such a total measure of positions of \mathbb{R}^r as the origin P of the moving frame attached to \mathbb{R}^r is contained in a unit cell \mathcal{V} and \mathbb{R}^r has common points with the unit figure \mathcal{E}^k . Taking the same procedure as in § 2.2, (2), we can obtain the limit equation by the covering procedure of the whole space E_n with the above foxmula (14), as follows,

$$\int_{P \in \mathfrak{P}} S_{k+r-n}(\mathfrak{E}^k \cap \mathfrak{R}^r) d\mathfrak{R} = \frac{\Omega_{n+1} \omega_{k+r-n}}{\omega_k \omega_r} S_k(\mathfrak{E}^k) S_r(\mathfrak{R}^r). \quad (15)$$

On the other hand, the total measure of \mathfrak{R}^r at such a position as P attached to \mathfrak{R}^r is contained in a unit cell of the system is given using (13), as follows,

$$\int_{P \in \mathfrak{P}} d\mathfrak{R} = \Omega_n C \quad (16)$$

where C denotes the n -dimensional volume of a unit cell. Dividing (15) with (16), we have the following theorem.

THEOREM 2. *When a r -dimensional manifold \mathfrak{R}^r whose r -dimensional volume is finite moves in E_n where a uniform- k -dimensional manifold \mathfrak{E}^k -system is defined, the mean value $S_{k+r-n}(\mathfrak{E}^k \cap \mathfrak{R}^r)$ of the $(k+r-n)$ -dimensional volume $S_{k+r-n}(\mathfrak{E}^k \cap \mathfrak{R}^r)$ of the intersection $\mathfrak{E}^k \cap \mathfrak{R}^r$ is given by*

$$\overline{S_{k+r-n}(\mathfrak{E}^k \cap \mathfrak{R}^r)} = \frac{\omega_n \omega_{r+k-n}}{\omega_k \omega_r} \cdot \frac{S_k(\mathfrak{E}^k) S_r(\mathfrak{R}^r)}{C}, \quad (17)$$

where $S_k(\mathfrak{E}^k)$ is the sum of k -dimensional volume of the figure set belonging to \mathfrak{E}^k and S_r the r -dimensional volume of \mathfrak{R} and C the n -dimensional volume of a unit cell.

Consequently, it has been definitely shown by the formula (17) that the above mean value is the same with one in the case that the uniform-figure-system is constructed by \mathfrak{R}^r as the fundamental figure and \mathfrak{E}^k is employed for the moving figure.

3.2 Special cases of the theorem (2).

(1) Case (1) $k=1, r=n-1$

Now, $r+k-n=0$, so that $S_{k+r-n}(\mathfrak{E}^k \cap \mathfrak{R}^r) = S_0(\mathfrak{E}^1 \cap \mathfrak{R}^{n-1})$ represents the number m of intersection-points of \mathfrak{E}^1 with \mathfrak{R}^{n-1} .

Therefore

$$\overline{m} = \overline{S_0(\mathfrak{E}^1 \cap \mathfrak{R}^{n-1})} = \frac{\omega_n \omega_0}{\omega_1 \omega_{n-1}} \cdot \frac{L F_{n-1}}{C} = \frac{\Gamma(\frac{n}{1})}{\Gamma(\frac{n+1}{2})} \frac{L F_{n-1}}{\Pi^{\frac{1}{2}} C}. \quad (18)$$

The formula gives the mean value of the number of the intersection-points of the moving hypersurface \mathfrak{E} of the $(n-1)$ -dimensional volume F_{n-1} with the curves of the uniform-curve \mathfrak{E}^1 -system defined by a curve-set of length L .

For $n=1$, \mathfrak{E}^0 reduces a set $\{P_i\}$ of some points, say $i=p$ and \mathfrak{E}^1 reduces a set of line-segments. Then m denotes the number of the points of \mathfrak{R} (P_1, P_2, \dots, P_p) which stand on the set \mathfrak{E}^1 at a moment. According to (18), we have $\overline{m} = \frac{pL}{C}$.

For $n=2$, \mathfrak{R}^1 reduces a set of curves of the total length l . Then, the mean value \overline{m} of the number of intersection point of with the uniform curve-system in the plane amount to $\frac{2lL}{\pi C}$.

This is in accord with the result in the plane by L. A. Santaló [3]. For $n=3$, \mathfrak{R}^2 reduces a set of surfaces of the total surface area F , the mean value \overline{m} of the intersection points of \mathfrak{R}^2 with the curves of the system is given by (18), as follows,

$$\bar{m} = \frac{LE}{2C}.$$

The result is identical with that which we obtained in the previous paper [5].

Case (II) $k=2$, $r=n-1$.

In the present case, $k+r-n=1$, so that $S_{k+r-n}(\mathfrak{E}^k \cap \mathfrak{R}^r) = S_1(\mathfrak{E}^2 \cap \mathfrak{R}^{n-1})$ represents curve length of intersections of \mathfrak{E}^2 with \mathfrak{R}^{n-1} .

Therefore

$$\bar{s} = \overline{S_1(\mathfrak{E}^2 \cap \mathfrak{R}^{n-1})} = \frac{\omega_n \omega_1}{\omega_2 \omega_{n-1}} \frac{S_2(\mathfrak{E}^2) S_{n-1}(\mathfrak{R}^{n-1})}{C},$$

or

$$\bar{s} = \frac{\pi^{\frac{1}{2}} \Gamma\left(\frac{n}{2}\right) F \cdot f_{n-1}}{2 \Gamma\left(\frac{n+1}{2}\right) C}, \quad (19)$$

where F is $S_2(\mathfrak{E}^2)$, precisely, the total surface area of \mathfrak{E}^2 and f_{n-1} is the $(n-1)$ -dimensional volume of \mathfrak{R}^{n-1} .

For $n=2$, $\mathfrak{R}^{n-1}=\mathfrak{R}^1$ reduces a set of curves of the total curve-length l . Then \mathfrak{E}^2 is a set of closed curves of the total plane area F . For s which is the mean value of the length of the curve segments which are included by the closed curves belonging to the uniform- \mathfrak{E}^2 -system, we have

$$\bar{s} = \frac{F \cdot l}{C}. \quad (20)$$

For $n=3$, $\mathfrak{R}^{n-1}=\mathfrak{R}^2$ reduces a set of surfaces of the total surface area f , \mathfrak{E}^2 is a set of surfaces of the total surface area F . In the present case, denotes the mean value of the length of the intersection-curves of moving \mathfrak{R}^2 with the uniform-surface \mathfrak{E}^2 -system. Then, we have

$$\bar{s} = \frac{\pi \cdot F \cdot f}{4C}. \quad (21)$$

This is the same with the result which we obtained in the previous paper [5].

4. Geometrical Probabilities.

4.1. Kinematic formula and geometrical probabilities.

Let us suppose that a uniform-curve-system is defined with a fundamental cell of n -dimensional volume and a fundamental curve-set of the total length L in E_n . Now, taking a convex hypersurface \mathfrak{R} of the $(n-1)$ -dimensional volume f_{n-1} which encloses a n -dimensional manifold \mathfrak{G}_1 of the volume V , let \mathfrak{R} move in the space E_n . Then, we can classify \mathfrak{R} 's position with reference to the uniform-curve-system into three cases as follows;

(i) \mathfrak{R} includes completely one or any pieces of curves belonging to the uniform-curve-system,

(ii) \mathfrak{R} has common points with the uniform-curve-system,

(iii) \mathfrak{G}_1 has no common point with the uniform-curve-system.

Let us estimate the probabilities P_i ($i=1, 2, 3$) for one of the above classified cases which may occur. For the purpose, we have the following kinematic formula (2) in

the euclidean space E_n by S.S.Chern,

$$\int K(D_0 D_1) \Sigma_1 = J_n \{ M_{n-1}^{(0)} V + M_{n-1}^{(1)} V_0 + \frac{1}{n} \sum_{k=0}^{n-2} \binom{n}{k+1} M_k^{(0)} M_{n-2-k}^{(1)} \}, \quad (22)$$

where

$$K(D_0 \cdot D_1) = I_{n-1} X(D_0 \cdot D_1).$$

In our case, we have following values for fundamental curve-set as the fixed figure Σ_0 ;

$$W_0 = 0, \quad M_i^{(0)} = 0 \quad (i = 1, 2, \dots, n-3) \quad M_{n-2}^{(0)} = \frac{\omega_{n-2} L}{n-1}, \quad M_{n-1}^{(0)} = \omega_{n-1},$$

and for the closed hypersurface \mathfrak{R} as the moving figure Σ_1 ; $V_1 = V$, $M_0^{(1)} = f_{n-1}$.

If we denote the number of the intersection points of \mathfrak{R} with the curves of the system by m in general, we have

$$K(D_0 \cdot D_1) = m \omega_{n-1}.$$

Moreover, according to our symbol, J_n equals to Ω_n . Then, the kinematic formula(22) reduces as follows,

$$\int_{\mathfrak{E}_1 \cap \mathfrak{E}^1 \neq \emptyset} m \dot{\mathfrak{R}} = \Omega_n V + \frac{\Omega_{n-1} \omega_{n-2}}{n-1} \cdot L \cdot f_{n-1}. \quad (23)$$

Now, let us suppose to take a domain $\overline{\mathfrak{U}}$ in the space E^n covered with the uniform-curve-system and denote the curve-set of the system in $\overline{\mathfrak{U}}$ by $\mathfrak{E}_{\overline{\mathfrak{U}}}^1$, then using (23), we have

$$\int_{\mathfrak{E}_1 \cap \mathfrak{E}_{\overline{\mathfrak{U}}}^1 \neq \emptyset} m \dot{\mathfrak{R}} = (\Omega_n V + \frac{\Omega_{n-1} \omega_{n-2}}{n-1} \cdot L \cdot f_{n-1}) \prod_i (\mu_i + 2\nu_i). \quad (24)$$

In the same manner as in § 2.2, (2), denoting by $\int_{P \in \mathfrak{P}} m \dot{\mathfrak{R}}$ such a total measure of positions of \mathfrak{R} as the origin P attached to \mathfrak{R} is contained in a unit cell \mathfrak{V} and \mathfrak{E}_1 has common points with some of the curves in \mathfrak{V} and taking the covering procedure of the whole space E_n with (24), we have the following limit equation,

$$\int_{P \in \mathfrak{V}} m \dot{\mathfrak{R}} = \Omega_n V + \frac{\Omega_{n-1} \cdot \omega_{n-2}}{n-1} L \cdot f_{n-1}. \quad (25)$$

Hereupon, we can divide the integral standing at the left side of (25) into tow parts, that is

$$\int_{\mathfrak{E} \subset \mathfrak{U}_1} \dot{\mathfrak{R}} + \int_{\mathfrak{E}^1 \cap \mathfrak{R} \neq \emptyset} m \dot{\mathfrak{R}} = \Omega_n V + \frac{\Omega_{n-1} \cdot \omega_{n-2}}{n-1} L \cdot f_{n-1},$$

where \mathfrak{E} represents any pieces of curves belonging to a unit cell.

On the other hand, the integral $\int_{\mathfrak{E}^1 \cap \mathfrak{R} \neq \emptyset} m \dot{\mathfrak{R}}$ can be written by (15) as follows,

$$\int_{\mathfrak{E}^1 \cap \mathfrak{R} \neq \emptyset} m \dot{\mathfrak{R}} = \frac{\Omega_{n+1} \omega_0}{\omega_{n-1} \omega_1} \cdot L \cdot f_{n-1}, \quad (26)$$

$$\int_{\mathfrak{E} \subset \mathfrak{E}_1} \dot{\mathfrak{R}} = \Omega_n V + \left(\frac{\Omega_{n-1} \cdot \omega_{n-2}}{n-1} - \frac{\Omega_{n+1} \cdot \omega_0}{\omega_{n-1} \cdot \omega_1} \right) L \cdot f_{n-1} \quad (27)$$

Then, using (10), (26) and (27), we have

$$\begin{cases} p_1 = \frac{V}{C} + \left(\frac{\Omega_{n-1} \cdot \omega_{n-1}}{n-1} - \frac{\Omega_{n+1} \cdot \omega_0}{\omega_{n-1} \cdot \omega_1} \right) \frac{L \cdot f_{n-1}}{C}, \\ p_2 = \frac{\omega_n \cdot \omega_0}{\omega_{n-1} \omega_1} \frac{L \cdot f_{n-1}}{c}, \\ p_3 = 1 - (p_1 + p_2). \end{cases} \quad (28)$$

For example, for $n=3$, we have

$$p_1 = \frac{4V - L f_2}{4C} \quad p_2 = \frac{L f_2}{2C}, \quad p_3 = \frac{4(C - V) - L f_2}{4C}.$$

The result is identical with the one which we obtained the previous paper in the space E_3 .

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